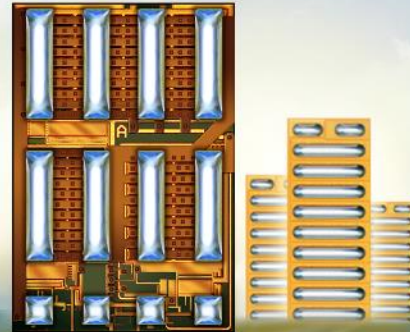


*The eGaN<sup>®</sup> Technology  
Journey Continues*



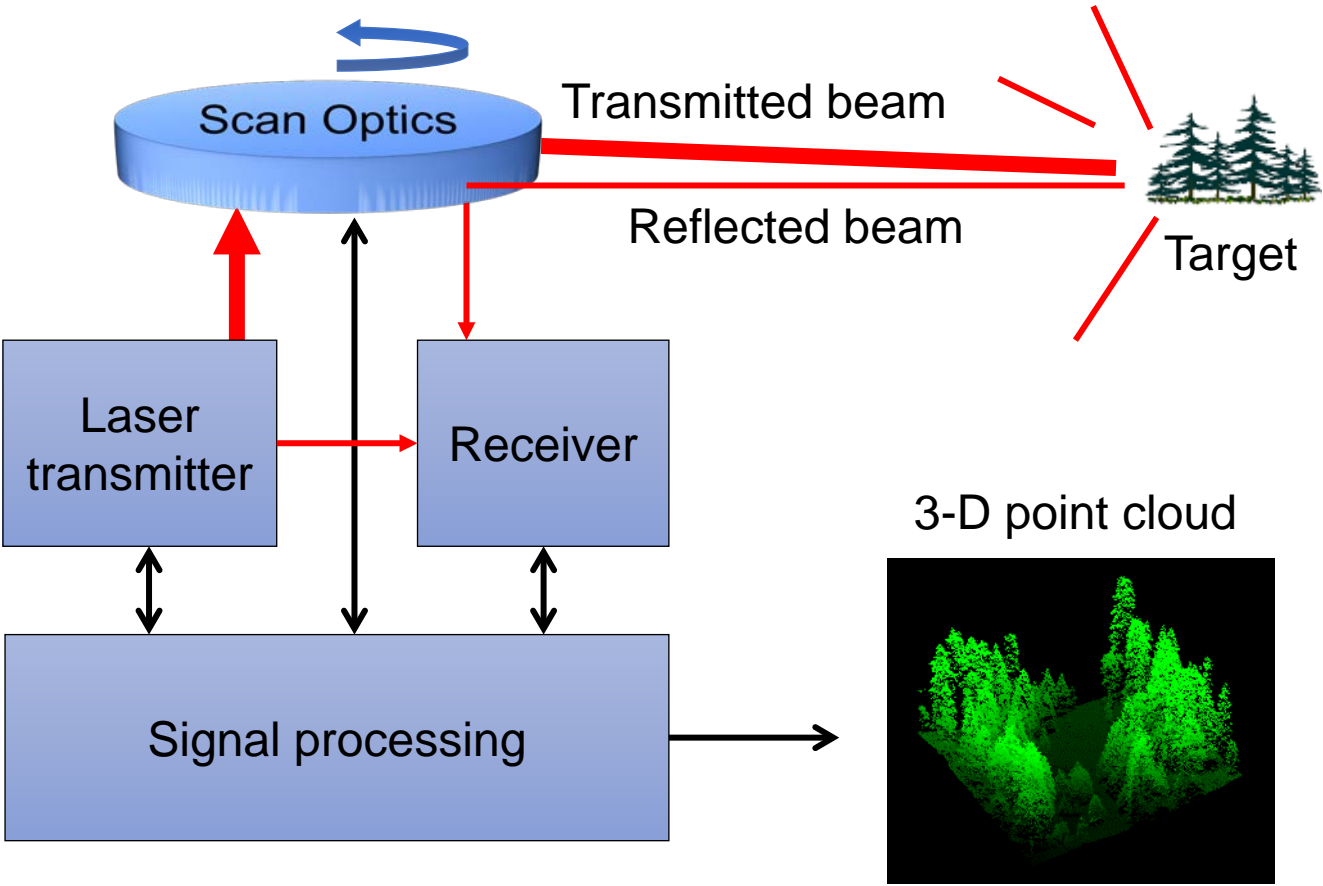
# Driverless Anything and the Role of Lidar

*Alex Lidow, Ph.D.  
CEO and Co-founder*

# Agenda

- What is lidar
- How lidar works
  - Signal
  - Scanning methods
  - Lasers
  - Detectors
- How lidar is integrated into autonomous cars
- The future

# What is Lidar?



[http://ucanr.edu/blogs/green//blogfiles/11605\\_original.png](http://ucanr.edu/blogs/green//blogfiles/11605_original.png)



# Where is Lidar Used Today?



SR

**Automated Guided Material Handling Robot**



SR

**Lidar Robotic Vacuum**



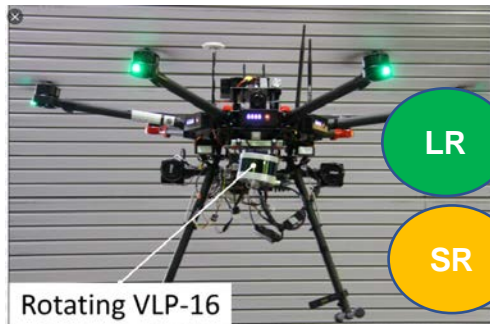
LR  
SR

**Lidar Robotic Delivery Vehicles**



LR  
SR

**Lidar Robotic Security Robot**



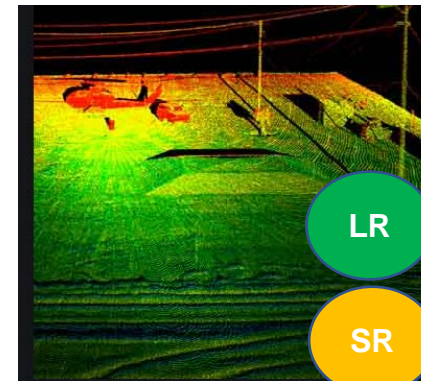
LR  
SR

**Drone Navigation and 3-D Mapping**



SR

**Humanoid Robots and Cobots**



LR  
SR

**Lidar Surveillance Systems**



LR  
SR

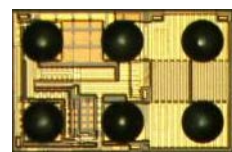
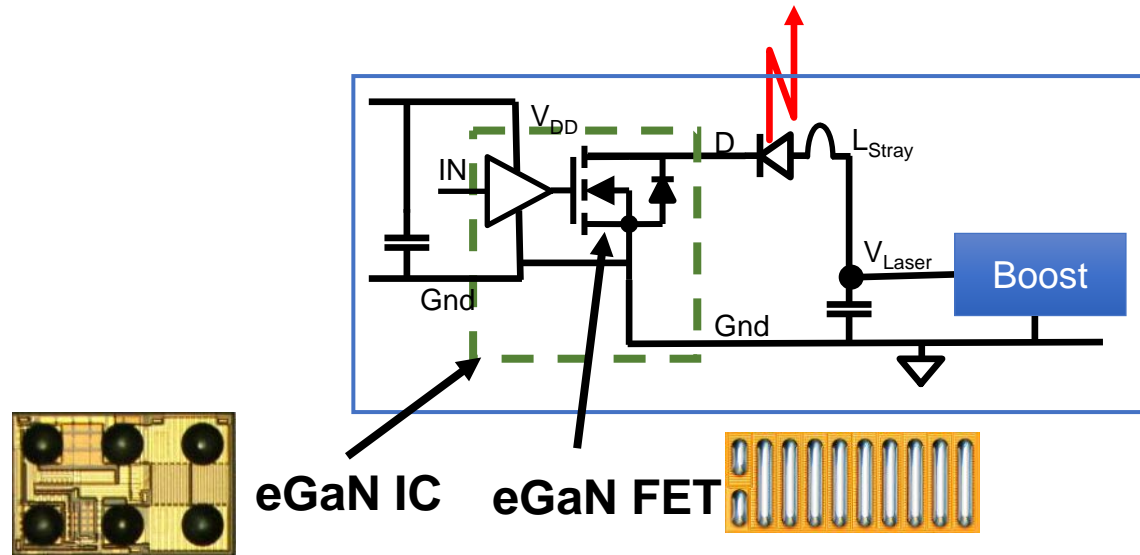
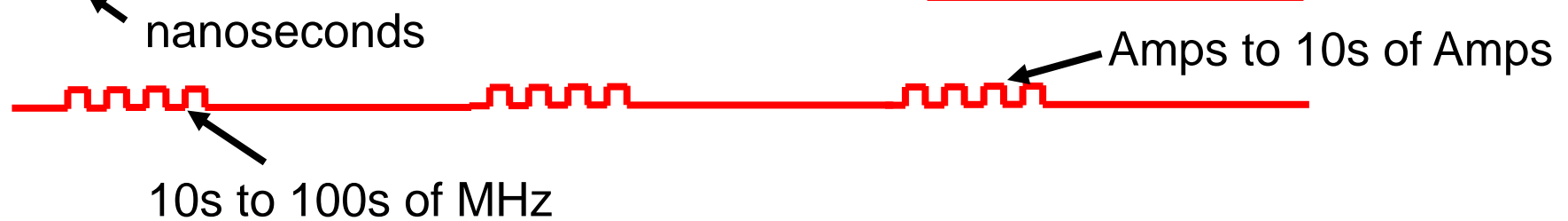
**Autonomous Vehicle Navigation**

# Laser Transmitter

Long range direct  
time of flight

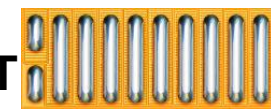


Short range indirect  
direct time of flight



eGaN IC

eGaN FET



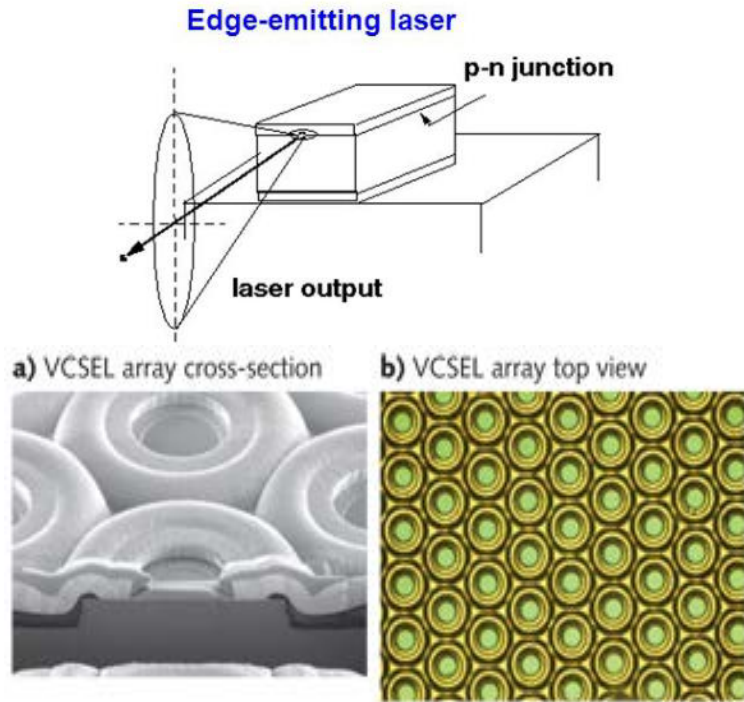
# Lidar Scan Methods



<https://spectrum.ieee.org/tech-talk/semiconductors/optoelectronics/mit-lidar-on-a-chip>



# Lasers



<http://www.laserfocusworld.com/articles/print/volume-50/issue-12/features/vcsels-for-manufacturing-high-power-vcSEL-arrays-make-ideal-industrial-heating-systems.html>  
Department of Physics, Texas Tech University

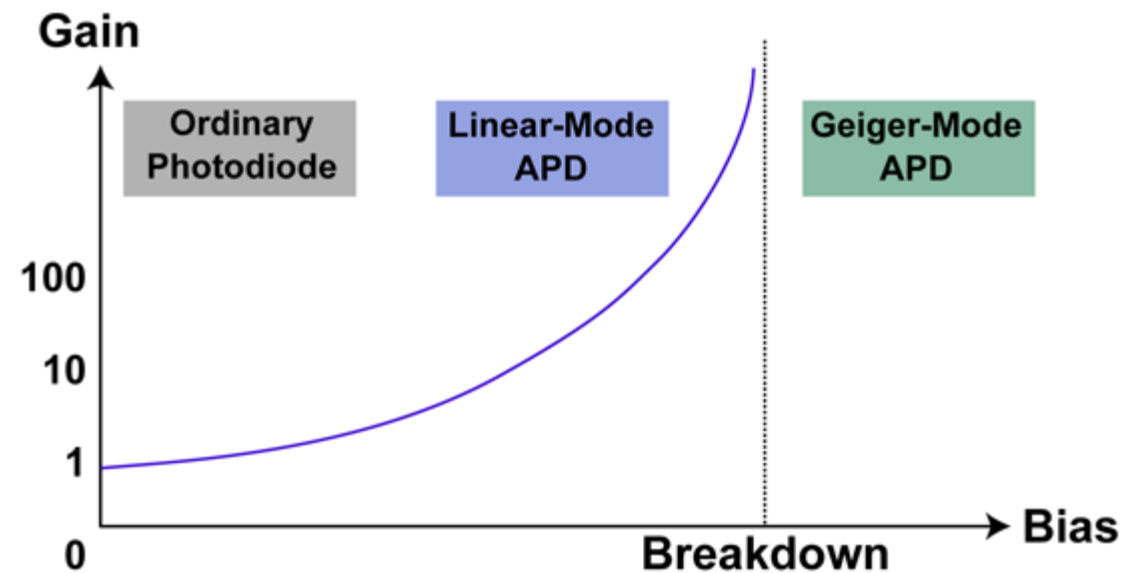


VGEN-SP

LIDAR Ytterbium Pulsed Fiber Lasers

# Detectors

- Photodiode
- Avalanche Photo Diode (APD)
- Geiger-Mode APD

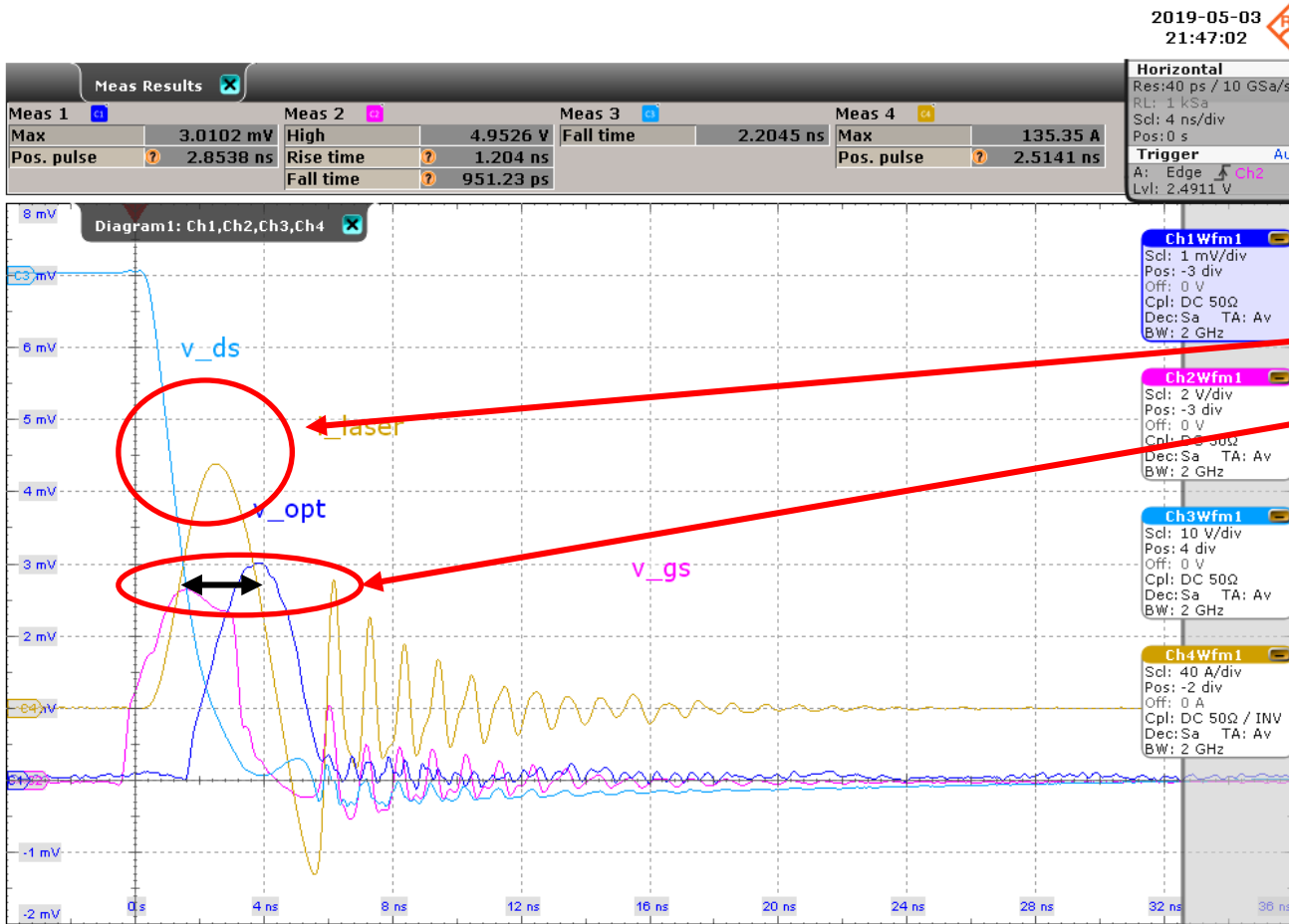




# Value of eGaN<sup>®</sup> Devices

- Long range lidar (scanning and spinning)
  - Very small with very high peak current
  - Very, very fast
- Short range lidar (ToF camera)
  - Very small size
  - Very high frequency capability
- *eGaN integration reduces size, increases speed, and reduces cost*

# Direct Time of Flight (DToF)

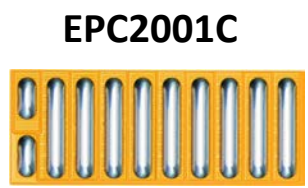


**EPC2001C**  
 Quad laser (all 4 in parallel)  
 OSRAM SPL S4L90A\_3 A01  
 $V_{bus} = 75 V$

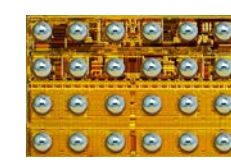
$I_{LASER,peak} = 135 A$  (total)

Current  $t_{pw} = 2.51 ns$

Optical  $t_{pw} = 2.85 ns$

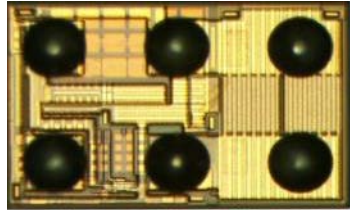


Discrete

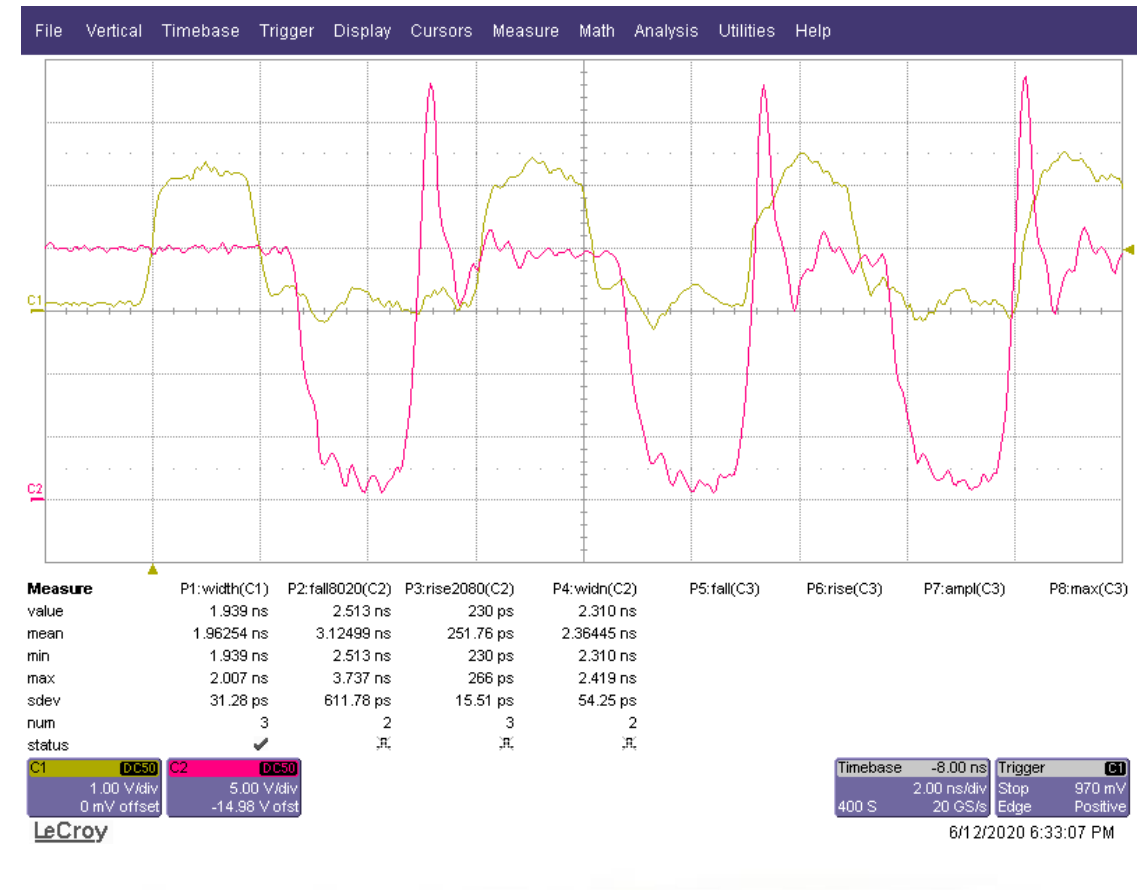
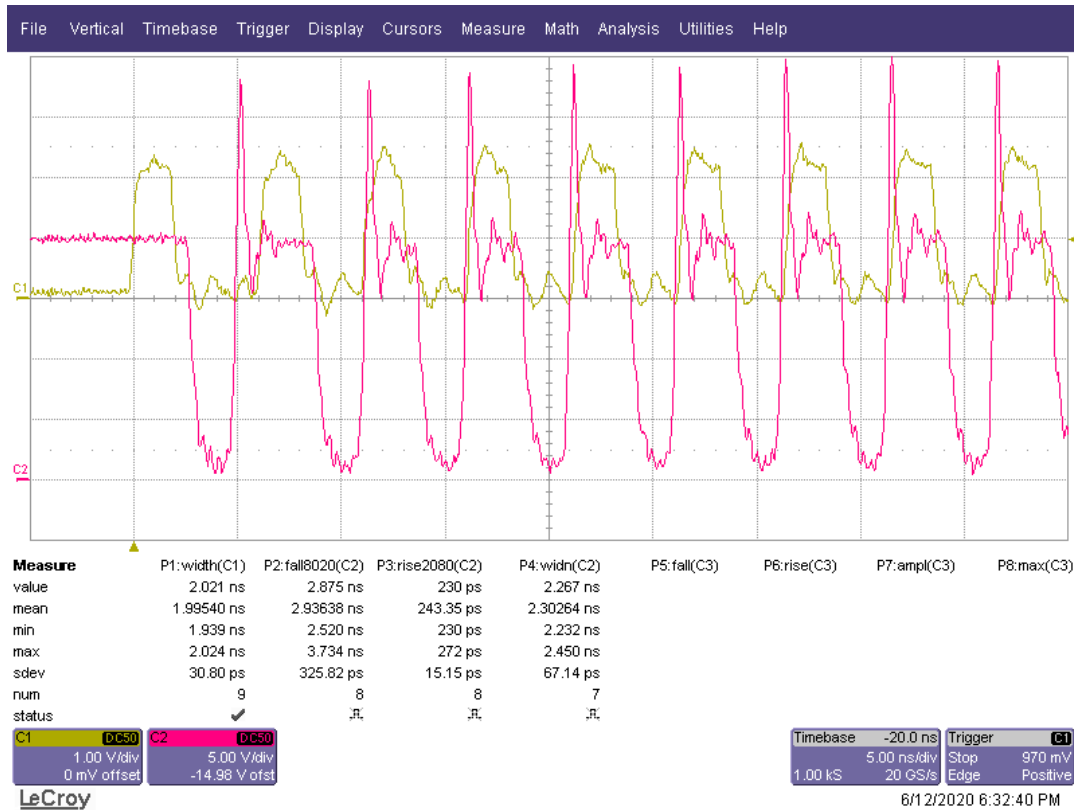


Dual Channel IC

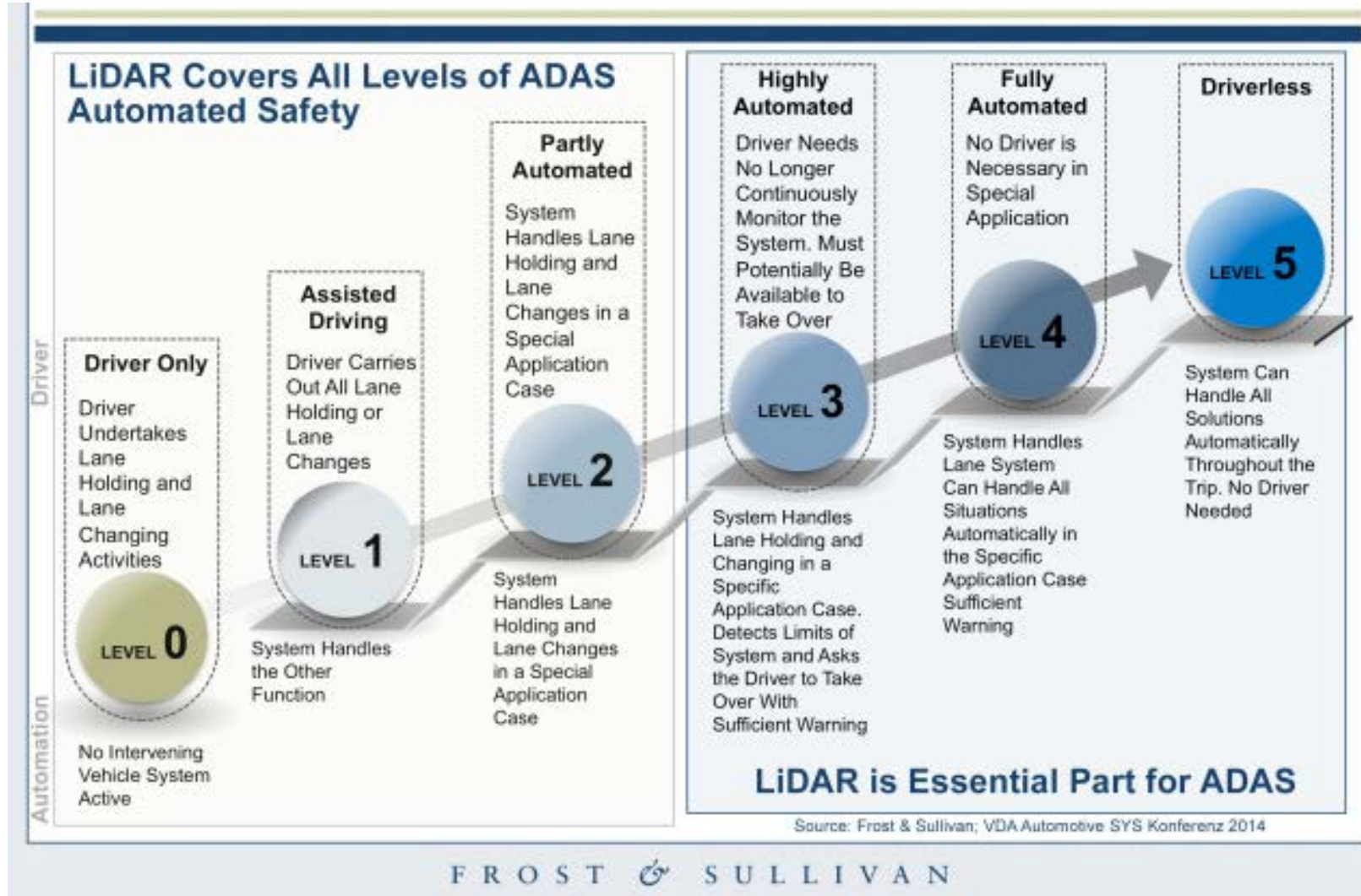
# IToF @ 200 MHz @ 9 A



## EPC21601 integrated laser driver



# The Pathway to Self Driving Cars





# What is Required for Autonomous Cars?



300 meters (approximately 11 seconds at 60 mph)

- Higher output lasers
  - Going to longer wavelengths (1440 nm vs 903 nm) allows for higher output power without danger to the human eye
    - 1440 nm lasers are more expensive
  - Edge emitting LEDs are more efficient than VCSEL and have superior columnation
    - VSEC lasers can be lower overall cost, but shorter range
- More sensitive detectors
  - Geiger mode can detect single photons but takes time to “reset”

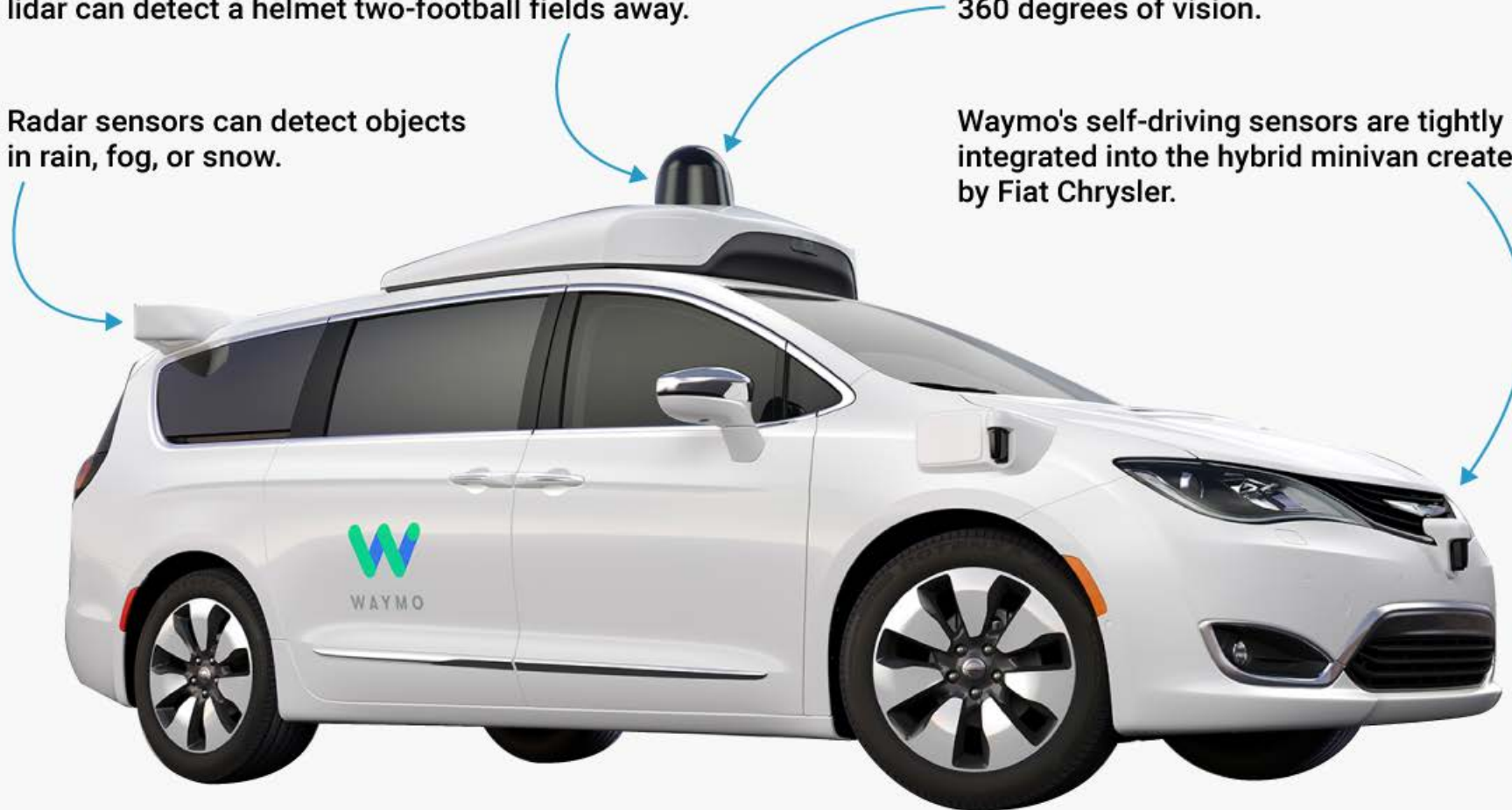
# How Waymo's Self Driving Car "Sees"

One of Waymo's three lidar systems that shoots lasers so the car can see its surroundings. Waymo says this lidar can detect a helmet two-football fields away.

A forward facing camera works with 8 others stationed around the car to provide 360 degrees of vision.

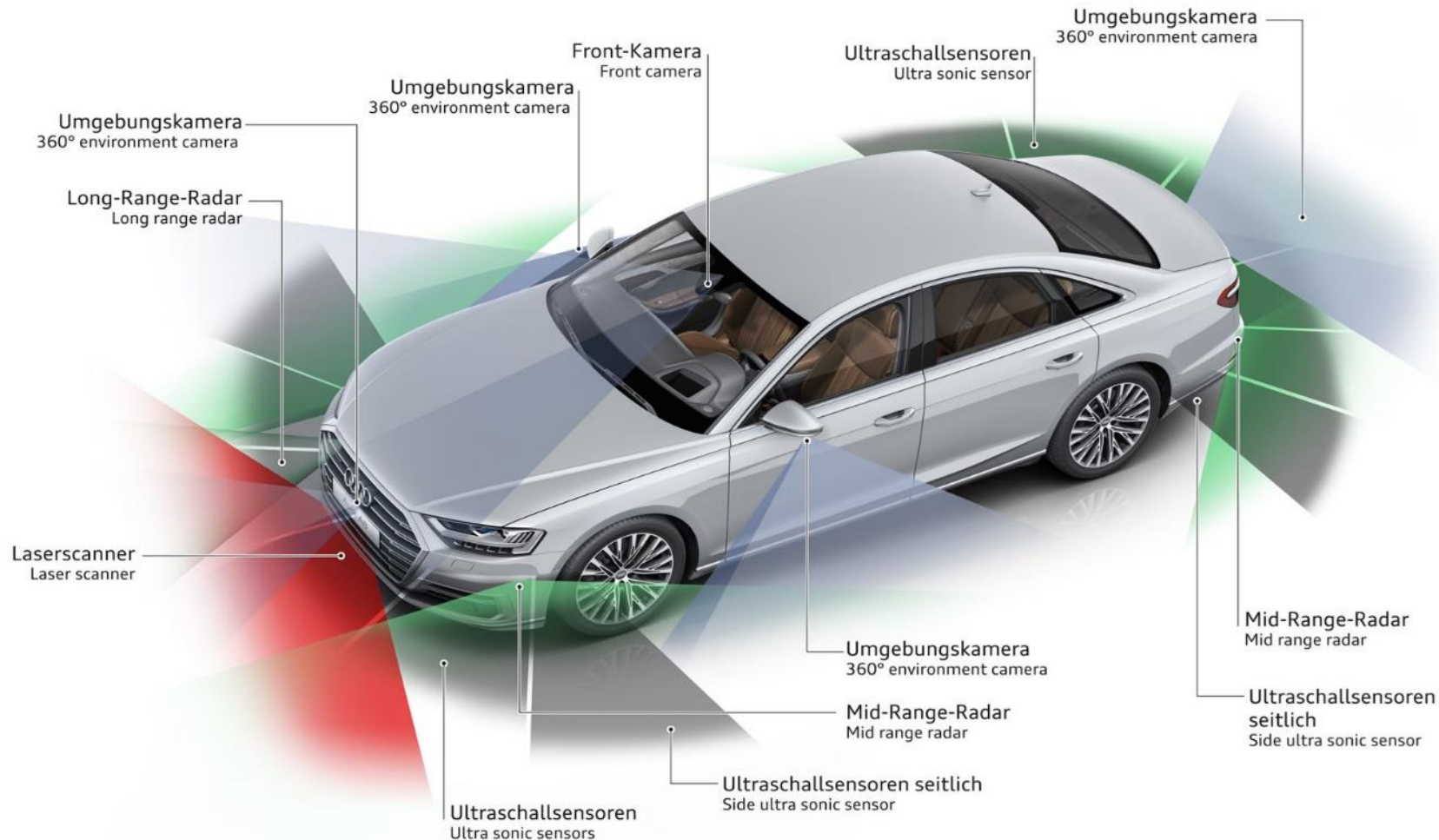
Radar sensors can detect objects in rain, fog, or snow.

Waymo's self-driving sensors are tightly integrated into the hybrid minivan created by Fiat Chrysler.



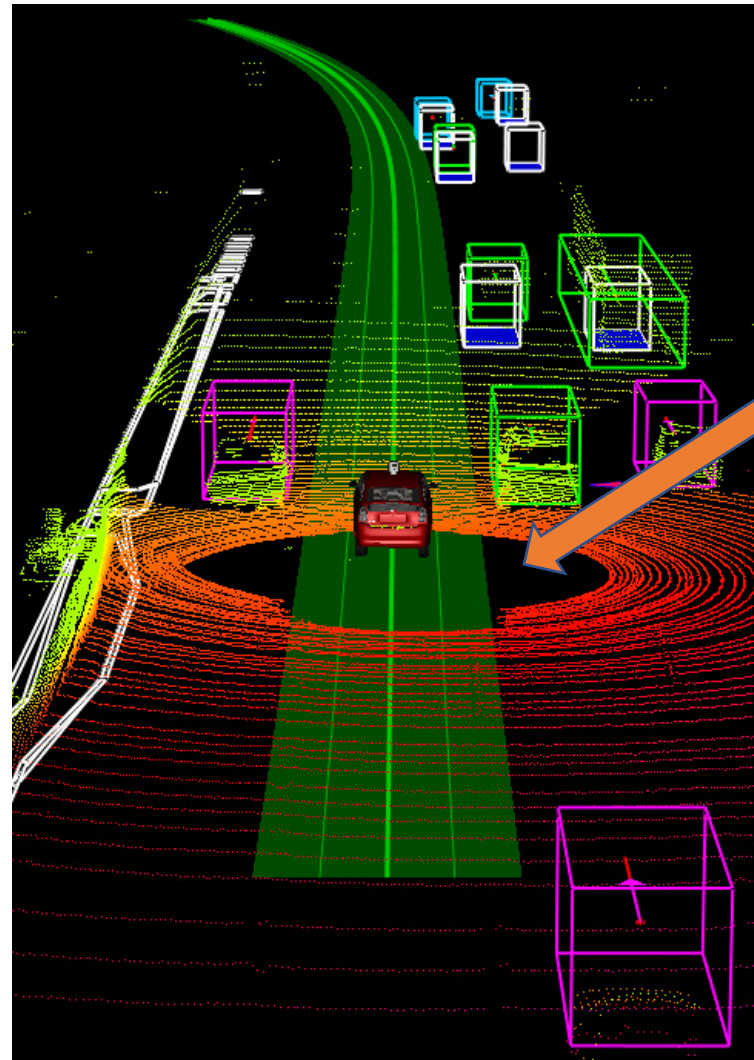
Source: Waymo

# How Audi's ADAS 3 A8 "Sees"



[http://images.car.bauercdn.com/pagefiles/74157/audi\\_a8\\_level3\\_01.jpg](http://images.car.bauercdn.com/pagefiles/74157/audi_a8_level3_01.jpg)

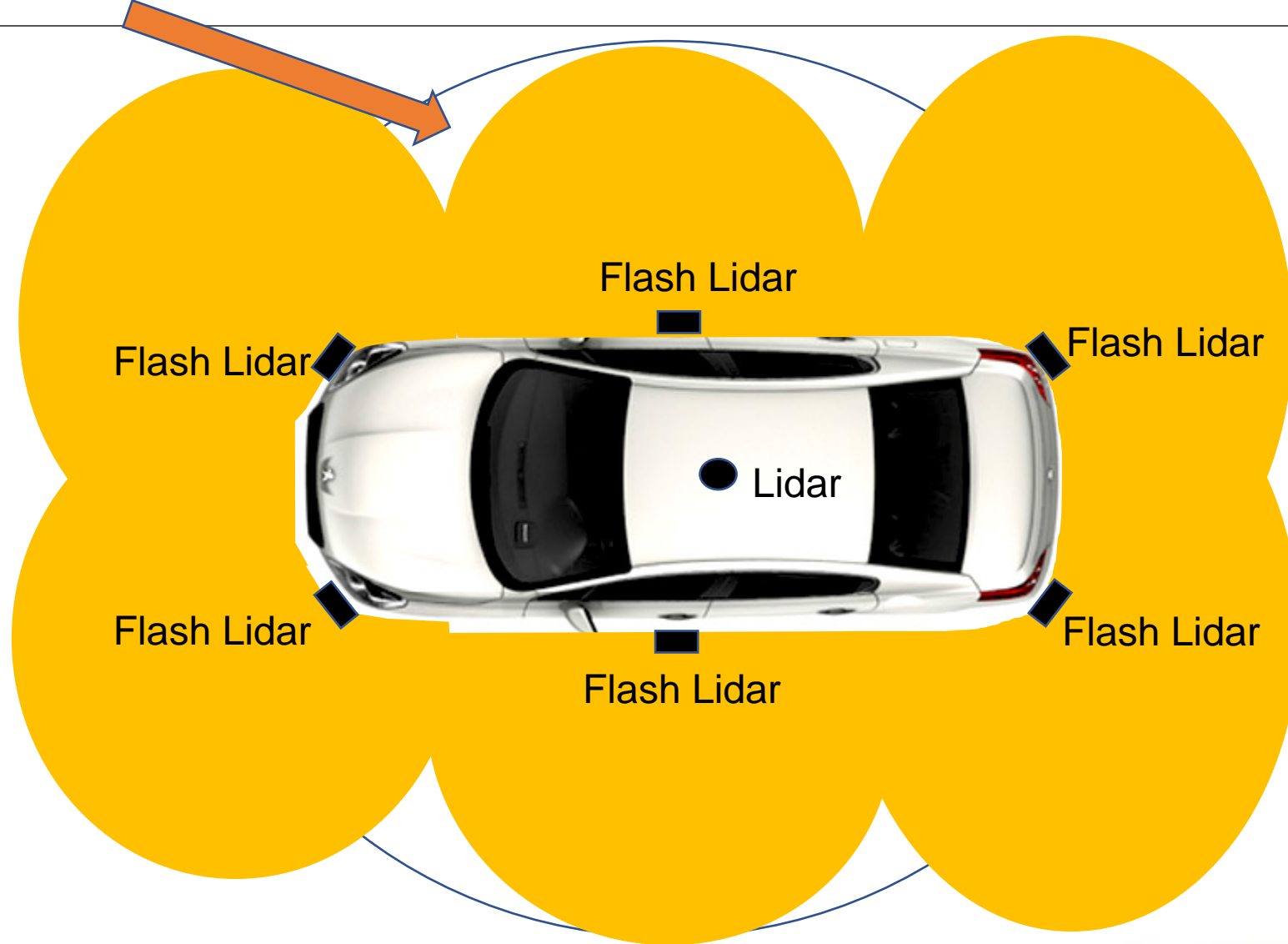
# How Lidar Might be Deployed



Shadow Zone



Shadow Zone



# Lidar Myths

- *Lidar can't see in fog, snow, or rain*
  - Lidar can see as well as, or better, than a human
- *Spinning disk lidar is unreliable*
  - There are lots of reliable spinning disks in every car
- *Lidar is too expensive*
  - Flash lidar is much less expensive than spinning lidar
  - Automotive companies have a way of grinding down cost

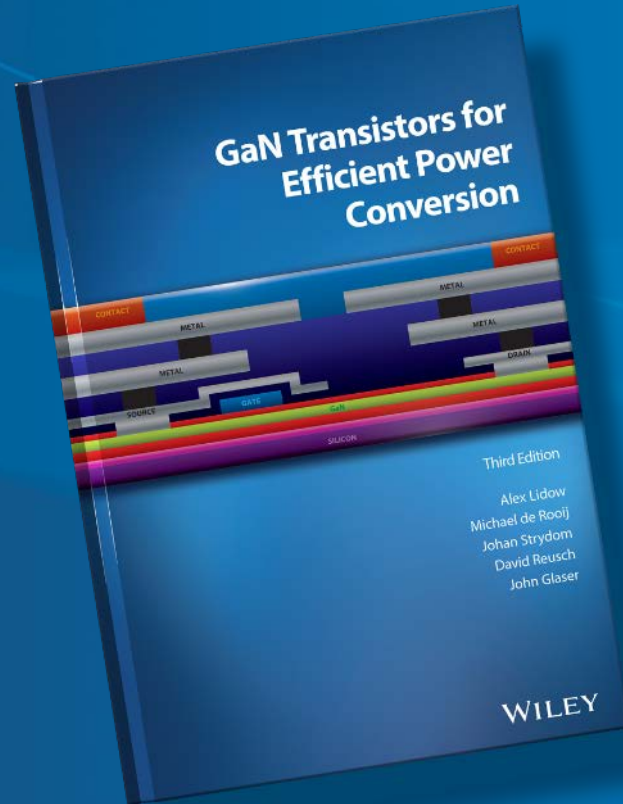
# The Future

- Lidar will be used on all cars and lots of robots and UAVs
- Lidar will be about as expensive as a headlamp
- Lidar (scanning) + lidar (flash) + camera will be able to handle most autonomous functions

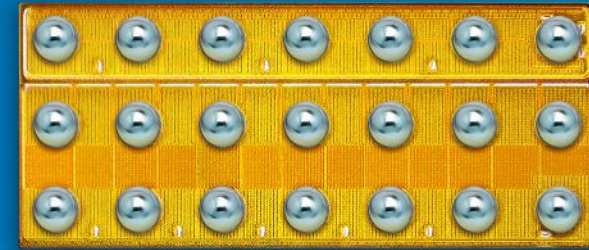


How To GaN Video Series

[epc-co.com](http://epc-co.com)



3<sup>rd</sup> Edition Textbook



eGaN<sup>®</sup> FETs and ICs

Evaluation Kits

